

A Model Proposal to Trawler Yachts from Hull form Importing to Superstructure, Interior Space Arrangement and Modeling With Set of Numerical Parameters

Seval Özgel Felek¹, Burçin Cem Arabacıoğlu²

¹ Architecture and Urban Planning Department, Architecture Restoration Program, Ordu University Unye Vocational School, Ordu, Turkey sevalozgelfelek@odu.edu.tr
² Architecture Faculty, Interior Architecture Department, Mimar Sinan Fine Arts University, Istanbul, Turkey burcin.arabacioglu@msgsu.edu.tr

ABSTRACT

In this study, parametric design with set of numerical parameters of trawler yachts design and modeling are presented. This parametric design is utilized to find a superstructure form and interior space design by considering hull, superstructure, lower deck, staircases and cocpit area. Within the scope of this study, the design phases are based on the desire to achieve a faster and more accurate result by creating a design process sequence according to the determined yacht typology. Based on the numerical values of the yacht form, it is aimed to make the superstructure and interior designs suitable for the desired typology. This study attempts to visualize trawler typology as a step to be taken by automatically modeling the desired typology. This approach does not completely replace the experts' design knowhow's but at least it suggests a guideline to initial layout of interior spaces and superstructure design.

Keywords: Trawler yacht, CAD, Modeling, Grasshopper, Interior space arrangement, Superstructure

1. INTRODUCTION

Trawler boats are used for fishing purposes. The trawler yachts that will be examined in the scope of the study are re-sesigned yachts used for pleasure by using the powerful features of the fishing boats. In the scope of the study, special purpose yachts will be examined; commercial, freight, passenger and fishing vessels shall be excluded.

Once the desired yacht type has been identified in the preliminary design phase, it is necessary to decide on the hull type and to search for previously made yachts that are similar to this yacht. The research is carried out by examining at least 10 yachts in the



required dimensions. Then, in order to reach the target yacht, average values are found for systematic analysis or graphic methods to find the main dimensions. The yacht's hull is a three-dimensional shape that is difficult to define simple mathematical expressions. Features of a craft; dimension, such as height, width and draft, or slenderness ratio (height / displacement) (Larsson & Eliasson, 2000).

Marine vehicles are a part of styling and interior design. The styling creates space by exterior form also affects exterior form by the partitioning and the incoming interior spaces. Without a distinction between the two, not only from inside to outside but also outside to inside must be worked. General arrangements should be made in accordance with the external filling and space positioning. If a typology is desired, styling dictates the characteristics of typology.

In the scope of the study, a model proposal will be done to make the styling and interior analysis of the trawler typology together to provide this integrity. The concept of partitioning, which is the most important issue in general arrangements, is being used with the inclusion of the design of head, back and machine bulkheads, as well as the arrangement of living areas, so that the vehicle can maintain its watertight integrity. Formation for the study, first of all database is created, styling and interior analyzes of 12-22 meter yachts with trawler typology will be carried. Superstructure and interior space partitioning will be done by applying parametric formulas and standarts obtained from sample yachts in database.

2. AUTOMATIC GENERATION OF SUPERSTRUCTURE AND INTERIOR SPACE DESIGN

Jo and Gero (1998) proposed using a genetic algorithm to solve allocation problems as formulating the design problem with n number of spaces.Lee et al. (2002) proposed an approach using a modified genetic algorithm as meeting the need of better space utilization. Daniels and Parsond (2006) proposed an approach to allocate spaces. Recently, Nam et al. (2010) proposed an approach to computerized preliminary design procedure of mid-size superyachts interior space arrangement. But all of the studies have been worked with two dimensions about interior space layouts. In this study, it is aimed to design three-dimensional mass settlements parametrically.

Yachts are masses with organic forms. While yacht is designing, thoughts sketched in papers and the three-dimensional modeling is started on the other hand. Yachts have angled walls and their sections are constantly changing. For this reason it is necessary to see what is going on with the three-dimensional model. This model proposal also



emerged to help the designers in the first stages of the design in which the ideas and the masses are decided. It is aimed to support the designer, not take the designer's job. Nam et al. (2010) mentioned that most interior designs are executed by some experts in advanced shipbuilding countries. Therefore, a preliminary guideline for the superyacht design is strongly desired to help the designer find a good starting point. Even the experts can verify their design using the guideline suggested here.

Yacht designers use the Rhinoceros program all over the world among the threedimensional modeling programs. Grasshopper, a free plugin in the Rhinoceros program that allows parametric design, is used to create this model proposal. The model is divided into five main parts: Hull, superstructure, lower deck, stairs, and cockpit area. Superstructure also have subparts: open deck walking area, main superstructure, handrail, superstructure deck floor. Lower deck also has subparts: bulkheads, floors, walls, beds, WC and cabinets.

2.1. Hull Form

Many publications regarding the parametric hull form design have been released. The study by Foster, I. T. (1979) titled 'Computer Aided Yacht Design' is one of the pioneering studies in this area. The work titled 'Numerical Investigation of a Systematic Model Series for Fast Monohulls' (1997) and' Parametric Design and Hydrodynamic Optimization of Ship Hull Forms' (1998) by S. Harries and D. Schulze, 'Parametric Generation of Yacht Hulls '(1997) was done by M. Bole. 'Parametric design of sailing hull shapes' (2006) was done by Mancuso, A. The work titled 'Automatic surface modeling of a ship hull' (2006) was done by F. Perez-Arribas, J. A. Suarez-Suarez and L. Fernandez-Jambrina. These studies are to develop ideas on how to make the hull form using computer aided methods. 'A Mathematical Model to Simulate Small Yacht Behavior' (1990) is a work by A. W. Browning that presents a mathematical model to simulate the behavior of small yachts on water.

On the other hand there are many geometric modeling systems used in naval architecture. Rhinoceros software is already used a lot in the Marine Industry. Not everybody is aware of the marine design capabilities of Rhino as a lot of users only apply Rhino in superstructure design or visualisation purposes by importing geometry in Rhino from other CAD tools. It is not designed specifically for naval architecture. FastShip, AutoShip, MaxSurf, MultiSurf, BEAN – The Virtual Shipyard, DELFTship, Pilot3D, ShipConstructor, MasterShip and MAAT 2000 softwaresare designed specifically for naval architecture. The aim is not use a program only prepared for the use of naval architects



but use a program with different modeling potentials. So the model proposal is integrated with the RhinoCeros program.

The first task was importing the hull to the model. The hull form is created by the naval architect according to the required dimensions and specifications in the desired program or any parametrical models and then converted to the 3dm extension that RhinoCeros can run to work in the proper format.

2.2. Superstructure

In order to examine the correct examples of the trawler yacht typology, the survey was limited to 12 to 22 meters. The first step was to collect the profile views of these trawler yachts. The most important of the trawler yacht manufacturers in the sector are: Selene, Grand Banks, Nordhavn, Kadey-Krogen. In order to resolve the yacht typology and settlements, these producers and modern trawler yacht brands will be investigated and a common deduction will be tried to be done.

Model	First	Second	Third	Fourth
	superstructure	superstructure	superstructure	superstructure
Nordhavn 40	-	x	х	x
Benetau Swift	х	x	-	х
44				
43 Heritage EU	х	x	x	x
41 Heritage EU	х	x	x	x
Selene 38	-	x	x	x
Nordhavn 43	-	x	х	х
Benetau Swift	х	x	-	х
50				
Selene 42	х	x	х	х
Euro Trawler	-	x	х	х
450ce				
Selene 45	-	x	х	x
Bering B50	-	x	х	х
Euro Trawler	-	x	х	х
550ce				
52 Heritage EU	x	x	x	x
Selene 49	-	x	x	x

Table.112-22-meter trawler yachts main superstructure partitioning



54 Heritage EU	х	х	x	х
Nordhavn 52	-	х	х	х
580	-	х	х	х
Bering B55	-	х	х	х
Euro Trawler	-	х	х	х
650ce				
610	х	х	х	х
Selene 54	-	х	х	х
Nordhavn 60	-	х	x	х
630	х	х	х	х
Selene 58	-	х	х	х
Nordhavn 64	-	х	х	х
B65	-	х	х	х
Selene 60	-	х	x	х
650	-	х	x	х
700	-	х	x	x

Nordhavn 40, Benetau Swift 44, 43 Heritage EU, 41 Heritage EU, Selene 38 have been examined for yachts ranging from 12 to 13 meters. Nordhavn 43, Benetau Swift 50, Selene 42, Euro Trawler 450ce have been examined for yachts ranging from 13 to 14 meters. Selene 45, Bering B50 have been examined for yachts ranging from 14 to 15 meters. The range of 15-16 meter trawler yachts has not been studied. Selected brands do not have yacht production at this size. Euro Trawler 550ce, 52 Heritage EU, Selene 49, 54 Heritage EU, Nordhavn 52 have been examined for yachts ranging from 16 to 17 meters. 580 and Bering B55 have been examined for yachts ranging from 17 to 18 meters. Euro Trawler 650ce, 610, Selene 54 have been examined for yachts ranging from 17 to 18 meters. Nordhavn 60, 630, Selene 58, Nordhavn 64, B65, Selene 60, 650 have been examined for yachts ranging from 20 to 22 meters First, second, third and fourth, the mass of superstructure was divided into 4 parts shown in Fig.1. 29 vessels between 12 and 22 meters are investigated and their superstructures are summarized in Table1.

The selected brands for the determination of the upper and lower limits of the parametric variables were examined according to the criteria shown in Fig.2.These values are tabulated, the minimum and maximum values are shown in Table 2.



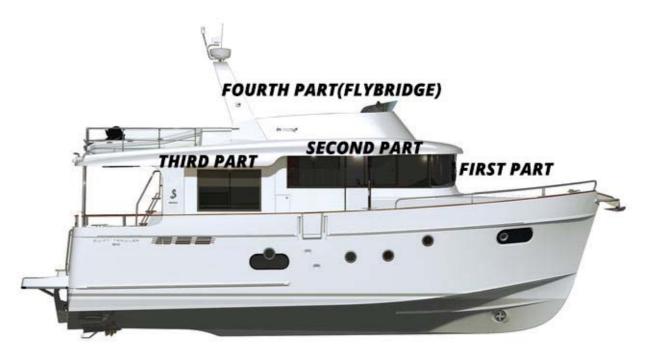


Fig.1 Main superstructure partitioning [URL-2]

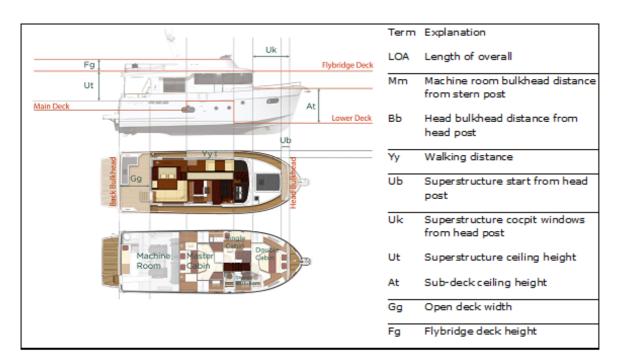


Fig.2 Analysis of the Benetau Swift 50 yacht upper structure and interior, terms are used in the schedules for expressions of values [URL-1]

Superstructure also have subparts: open deck walking area, main superstructure, handrail, superstructure deck floor. Open deck walking area: In order to create an superstructure, the border must first be specified. This boundary starts to form the walking distance of the open deck. In order to create this distance, the upper surface



curve of the hull is drawn again and the first variable is defined. Offset is applied up to the desired distance.

	Mm	Bb	Yy	Ub	Uk	Ut	Gg	Fg	At
Min	370	90	30	40	245	190	130	55	185
Value	cm	cm	cm	cm	cm	cm	cm	cm	cm
Мах	1065	322	84	511	654	250	420	244	230
Value	cm	cm	cm	cm	cm	cm	cm	cm	cm

Table.212-22-meter trawler yachts superstructure min and max values

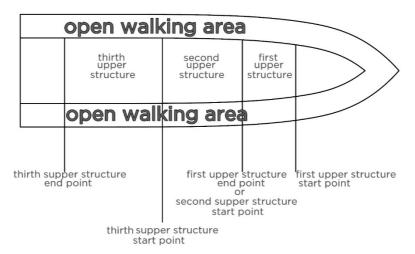


Fig.3 Main superstructure parameters

For main superstructure as a result of Table 1, it can be seen that the first and thirth superstructures are in some models, with the second and fourth superstructures present in every trawler. The parameters must be set so that these four can also be created. It was also found that the first superstructure was inclined due to the difference in front and back heights. When looking at the cockpit windows of the second superstructure, it was seen that there were vertical, front angled or back angled glasses. In the third superstructure that there were vertical, front angled or back angled structure. The parameters for first upper structure is beginning of the structure, frot height and back height for making angled structures. If first superstructure doesn't want, values have been set to be entered 0 and the creation of the second superstructure has been continued. The parameters for second and thirth upper structure is beginning and ending of the structure, height of the structure and if there is angled glasses, the angle value variable needed (Fig.4). The parameters for fourth upper structure and if there is angled glasses, the angle value variable needed. And also, second superstructure front and



thirth superstructure side glasses numbers and window platen width added to variables. Superstructure variables are summarized in Table 4.

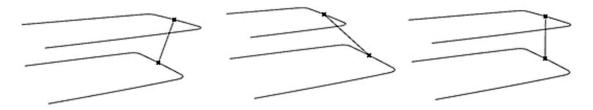


Fig.4 Main superstructure angled or vertical structures

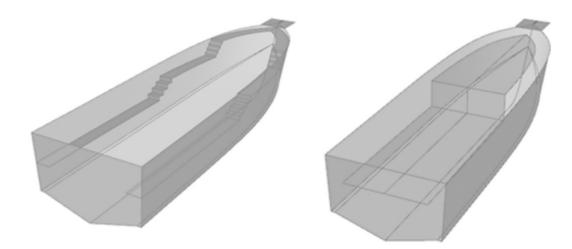
2.3. Handrails

Handrail is located on the entrance deck for safety on yachts head of the yacht and on the third superstructure. The handrail on the entrance deck starts at the head of the yacht and continues until the second super structure. This distance information was determined in the previous steps. The outer curvature of the hull is cut according to this distance information and is moved on the z axis according to the height variable. And it is automatically modeled without asking user of the radius dimension. The second handrail on the third superstructure modeled in the same way.

2.4. Upper deck floors

There has been upper deck exterior and interior decks when the samples were examined. When the 12-22 meter trawler samples are examined by upper exterior deck, there is not a single deck, especially on these surprisingly decked yachts. There is a variable number of digits between these decks. In terms of flexibility, it can be made according to the variables given to one, two or three decks. Since it is a structure rising from the bottom to the top, the point is moved on the z-axis relative to the distance from the bottom of the yacht hull. This point is the most midpoint of the back of the yacht. This point is moved along the x-axis according to the stern distance of the first deck (Fig. 5) This point is moved along the x and z axes according to the value of the step height and the step width (Fig. 5) If the third deck is present, it is moved along the x and z axes according to the step width; If there is no third deck, the remaining distance is calculated and continued until the surface is reached. On the other hand, upper interior deck has only one or mostly two decks on the inside floors. These deck formations can be made according to given variables.





Eia E llooar	ovtorior	and	intorior	dock floors
Fig.5 Upper	exterior	anu	Interior	

Model	At	Master cabin	Double cabin	Single cabin	Kitchen	Communal bathroom	Storage/ Common Area
Nordhavn 40	195 cm	Existing	1	None	None	Existing	None
Benetau Swift 44	190 cm	Existing	1	None	None	Existing	None
43 Heritage EU	175 cm	Existing	1	None	None	1	Existing
41 Heritage EU	175 cm	Existing	1	None	None	None	None
Selene 38	189 cm	Existing	1	None	None	Existing	Existing
Value Ranges	175- 195 cm	Existing	1	None	Existing/ None	Existing	Existing/ None
Nordhavn 43	195 cm	Existing	1	None	None	Existing	None
Benetau Swift 50	190 cm	Existing	1	1	None	1	None
Selene 42	192 cm	Existing	1	None	Existing	Existing	Existing
Euro Trawler 450ce	190 cm	Existing	1	None	None	Existing	None
Value Ranges	190- 195 cm	Existing	1	Existing/ None	Existing/ None	Existing	Existing/ None
Selene 45	180 cm	Existing	1	None	None	Existing	None
Bering B50	220 cm	Existing	2	None	None	Existing	None
Value Ranges	180- 220 cm	Existing	1 /2	None	None	Existing	None
Euro Trawler 550ce	220 cm	Existing	2	None	None	Existing	None
52 Heritage EU	185 cm	Existing	1	1	None	1	Existing
Selene 49	180 cm	Existing	1	None	None	Existing	None
54 Heritage EU	190 cm	Existing	1	1	None	1	Existing
Nordhavn	200	Existing	1	None	None	None	None



Value Ranges	185- 220 cm	Existing	1 /2	Existing/ None	None	Existing/ None	Existing/ None
580	195 cm	Existing	2	None	None	Existing	None
Bering B55	230 cm	Existing	2	None	None	Existing	None
Value Ranges	195- 230 cm	Existing	2	None	None	Existing	None
Euro Trawler 650ce	220 cm	Existing	2	None	None	Existing	None
610	200 cm	Existing	2	None	None	Existing	None
Selene 54	195 cm	Existing	2	None	None	Existing	None
Value Ranges	195- 220 cm	Existing	2	None	None	Existing	None
Nordhavn 60	210 cm	Existing	1	None	None	None	None
630	200 cm	Existing	2	None	None	Existing	None
Selene 58	195 cm	Existing	2	None	None	Existing	None
Nordhavn 64	210 cm	Existing	2	None	None	Existing	None
B65	220 cm	Existing	1	1	None	Existing	None
Selene 60	200 cm	Existing	2	None	None	Existing	None
650	200 cm	Existing	2	None	None	Existing	None
Value Ranges	195- 220 cm	Existing	1/2	None / 1	None	Existing/ None	None
700	200 cm	Existing	2	None	None	None (every cabin has its own)	None
Value Ranges	200 cm	Existing	2	None	None	None	None
ALL VALUE RANGES	175- 220 cm	Existing	1/2	None / 1	Existing/ None	Existing/ None	Existing/ None

2.5. Interior design

The selected brands for the determination of the interior design parametric variables were examined according to the master cabin, single cabin, kitchen, communal bathroom, storage/common area existance criteria shown in Table 3. The value ranges of the 12-22-meter trawler yachts are given also in the same table. The values vary according to the design of each model. It is very difficult to determine an average value. When looking at the interior layout, however, only the presence of the master cabin can be mentioned. Apart from this, one or two double cabins can also be mentioned or single cabin. Communal bathrooms are available on some samples. There is only two example has kitchen or storage area on the lower deck in any case.



2.6. Lower deck

To designate lower deck, the space between engine room and head bulkhead must know. Head bulkhead, engine room bulkhead and engine room walls are modelled parametrically. The head bulkhead is according to the rules of implementation for the technical characteristics of the ships; In general, the watertight impact range is not less than 0.05L, not more than 0.1L from the head. The minimum and maximum values of the variable are set according to these calculations. The knowledge of how much space we need for the width of the engine room space is taken from the naval architecture. In this information frame, the machine bulkhead created using the stern distance of the wall. To designate lower deck floor, the height variable from the bottom of the yacht is enough. The surface extruded by this height is cut by the hull to form the deck floor (Fig. 6).

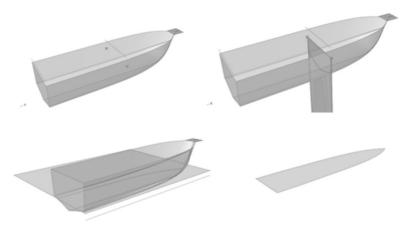


Fig.6 Back bulkhead and lower deck floor formation

For interior wall partitioning, the location of the trawler yachts between 12 and 22 meters was examined. It has been investigated how many vertical and horizontal divisions should be made as shown in Fig. 7 in order to be able to make a suitable partition for the yachts with the most interior spaces. As a result, dividing 3 divisions horizontally into 4 vertically will allow both the implementation of the model with the most interior space and the implementation of the model with the least interior space.

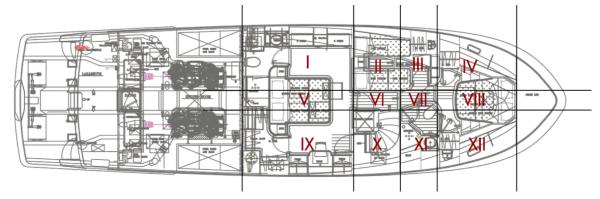


Fig.7 Trawler yacht interior wall partitioning



To create vertical walls, back bulkhead line is used and moved from this wall using the distance variable. This line reflected to the upper deck floor and also onto lower deck floor. The surface to be created between these two new lines formed the first vertical wall (Fig. 8).Vertical walls are constructed in the same way. Wall 1 is defined by its distance from the wall of the back bulkhead, wall 2 is defined by its distance from wall 1, and wall 3 is defined by its distance from wall 2.To create horizontal walls, this space is divided into maximum three parts. The line which connected back bulkhead and vertical wall 1 is used to create the walls. This line is moved according to the Y distance variable. It is reflected to the upper deck floor. As in the vertical wall, the thickness is given by 5 cm displacement and the surface is created. This surface is split with the lower deck floor. It won't be possible to create the example in Fig. 13 in this case for wall partitioning. For this reason, vertically formed walls are horizontally divided into 3 pieces by cuts, and giving angle to each piece.

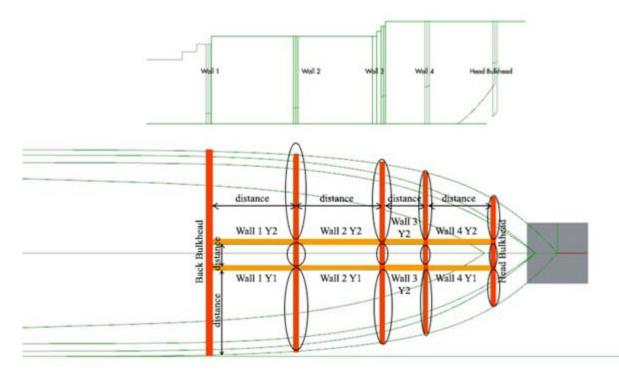


Fig.8 Wall partitioning

Modules that can be automatically added to each volume created in the interior are decided. These modules are set as cabinet, bed and WC. The cabinets are fitted with width, height and depth variables, position variables, and positioning in any size and position, in accordance with each module to be added. It is possible to add 8 cabinets in 12 sections. Bed types used in yachts were examined, dimensions were connected to the standard; There are 6 alternatives, single, double, single-angled, double-angled, single berth beds and double narrow beds. It is possible to add 4 beds to the model. The



position and angle of the added beds can be changed. The types of WC used in yachts are examined, dimensions are connected to the standard; wall mounted, electrical large and small, marine type large and small WC 5 alternatives are offered. 3 WCs can be added to the model. It is ensured that the position and angle of the inserted WCs can be changed. Modules such as washbasins and washrooms located in wet spaces are not added to the model. Especially the shower areas are specially manufactured for the yacht depending on the geometry of the vessel and without using standard shower yachts. Very rarely ready-made products are used. The use of washbasin is sometimes made with ready-made products, mostly with booth-specific countertops. The purpose of the model is to prepare the draft of the general layout by adding the masses that can be prepared and connected to the standard. The seating area and kitchen areas on the upper deck are excluded from the model due to the same reasons. Flybridge has been added to the model by changing the position change and height on the superstructure. Cockpit area and cockpit seat were also added to see the mass and general layout. Cockpit control areas used in yachts are reviewed and 3 alternatives are presented: right-based, left-based and covering the whole area. The depth and height of the cockpit seat are kept constant, and the width, back height and position can be changed.

In this study, grasshopper commands and their relations used in modeling phases of walls, floors, stairs, superstructure, interior fittings are not given in detail in the article. What is important for the study is what variables are needed. As shown in Table 4, a total of 110 variables are needed for superstructure and interior space layouts. New variables for each new module added will also be added to this variable numbers.

3. COMPARISON OF THE YACHT MADE BY MODEL PROPOSAL AND THE MAIN YACHT

Selene 49 yacht was created with the model proposed in the article. The model with the main boat was constructed with profile, lower deck plan, upper deck plans.For better understanding the comprehension of the profile comparison, as seen in Fig. 9, the Selene 49's hull is assembled instead of the model's hull. Fig. 10 shows the comparison of upper deck layout of Selene 49 and the model yacht.





Fig. 9 Selene 49 and the model profile comparison [URL-3]



Fig. 10 Selene 49 upper deck layout and the model comparison [URL-3]



Figure 11 and Figure 12 shows the comparison of lower deck layout of Selene 49 and the model yacht.



Fig. 11 Selene 49 lower deck layout and the model comparison [URL-3]



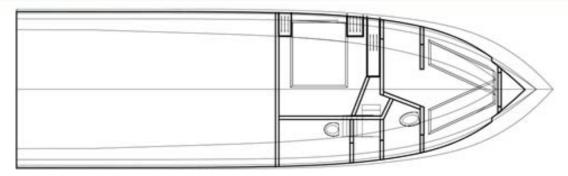


Fig. 12 Selene 49 lower deck layout alternative 2 and the model comparison [URL-3]



4. CONCLUSIONS

Research on the hull modeling and interior space arrangement was carried out to provide a background of the preliminary trawler yacht design. A computerized design system for superstructure and interior space arrangement with 3d modelling was developed. In the Rhinoceros software, this model proposal was created using the Grasshopper plugin commands that allow parametric design by this software. Within the scope of this model proposal, work is started by importing the naval architect's hull into the model. The formation of the upper structure, the placement of the floors on the desired height and floors, the descent to the lower deck and the stairs that lead to the flybridge have been established. With the lower deck head and back bulkheads installed, the remaining floor areas were made vertical and horizontal to form the walls. In line with general layout principles, the settlement has been established with the main lines of cabins, WC and bathrooms.

Yacht design is a design that does not have flat walls and floors, which requires threedimensional thinking. Decisions made with two dimensional drawings do not reach the correct conclusion because they have organic forms. This model has been created in order to be able to overcome these problems while still in the sketch phase and to see how the decisions to be given outline affect the external and internal design of the yacht. Designers are advised to be able to make faster and more accurate decisions and gain speed in their work. By changing the variables repeatedly, it is possible to perform many alternatives quickly. As a result, both 3D models can be reached and plan and crosssection output can be obtained.

There are few experienced designers in yacht design especially in interior and superstructure design. However, the field of yacht design is one of the fastest growing economies in the world and it is necessary to carry out studies for designers and also naval architects to serve this area. It is thought that a basic design guideline can help designers and contribute to this field.

Table.4 Superstructure and interior design variables for parametrization

		structure a		-				
		First .	Second	Thirth	Fourth			
	Walkin	superstruc	superstruc	superstruc	superstruc			
	g area	ture	ture	ture	ture			
			Second		Fourth			
		First	superstruct		superstruct			
	Open	superstruct	ure		ure (fly			
	walking	ure	beginning		bridge)			
	area	beginning	point from		beginning			
	width	point from	head if first		point from			
		head	superstruct		head			
			ure doesn't					
			exist					
		First	Second	Thirth	Fourth			
		superstruct	superstruct	superstruct	superstruct			
		ure length	ure length	ure length	ure length			
SUPERSTRUC		First	Second	Thirth	Fourth			
TURE		superstruct	superstruct	superstruct	superstruct			
		ure head	ure height	ure height	ure height			
		height			-			
		First	Second	Thirth	Fourth			
		superstruct	superstruct	superstruct	superstruct			
		ure back	ure angle	ure angle	ure angle			
		height	(+, -, 0)	(+, -, 0)	(+, -, 0)			
			Second	Thirth				
			superstruct	superstruct				
			ure front	ure side				
			glass	glass				
			number	number				
			Second	Thirth				
			superstruct	superstruct				
			ure glass	ure glass				
			platen	platen				
-			width	width				
	Entran	Third						
	ce	superstruc						
	handra 	ture						
	il	handrail						
	Entranc	On the third						
HANDRAILS	е	superstruct						
	handrail	ure handrail						
	length	length						
	Entranc	On the third						
	е	superstruct						
	handrail	ure handrail						
	height	height						
	Upper	Upper						
	deck	deck						
UPPER DECK	exterio	interior						
FLOORS	r							
	Upper	Upper deck						
	deck	interior first						
	exterior	floor height						





	1	1	1		1				
	first								
	floor								
	height								
	Upper								
	deck								
	exterior	Upper deck							
	first	interior first							
		floor length							
	floor								
	length								
	Upper								
	deck	Upper deck							
	exterior	interior							
	second	second							
	floor	floor height							
	height	_							
	Upper								
	deck								
	exterior								
	second								
	floor								
	length								
	Upper								
	deck								
	exterior								
	thirth								
	floor								
									Coc
	floor	Lower	Walls	Bods	Cabinet	WC	Stairca	Cocpit	Coc
	floor height	Lower deck floor	Walls	Beds	Cabinet	wc	Stairca se	Cocpit	pit
	floor height Bulkhe		Walls	Beds	Cabinet			Cocpit	
	floor height Bulkhe ads		Walls	Beds	Cabinet	Alterna	se	Cocpit	pit
	floor height Bulkhe ads Head		Walls	Beds	Cabinet	Alterna tive 1:	se Alterna		pit
	floor height Bulkhe ads Head bulkhea		Walls Wall 1	Beds	Cabinet	Alterna tive 1: WCL2	se Alterna tive	Alterna	pit
	floor height Bulkhe ads Head bulkhea d	deck floor		Beds		Alterna tive 1: WCL2 (wall	se Alterna tive 1: Strai	Alterna tive 1:	pit
	floor height Bulkhe ads Head bulkhea d distance	deck floor Height from	Wall 1 distance	Alternative	Cabinet	Alterna tive 1: WCL2	se Alterna tive 1: Strai ght	Alterna tive 1: Left	pit seat Seat
	floor height Bulkhe ads Head bulkhea d	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:		Alterna tive 1: WCL2 (wall	se Alterna tive 1: Strai	Alterna tive 1:	pit seat Seat widt
	floor height Bulkhe ads Head bulkhea d distance	deck floor Height from	Wall 1 distance	Alternative	Cabinet	Alterna tive 1: WCL2 (wall mounte	se Alterna tive 1: Strai ght	Alterna tive 1: Left	pit seat Seat
	floor height Bulkhe ads Head bulkhea d distance from	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d	Se Alterna tive 1:Strai ght staircas	Alterna tive 1: Left hand	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d electric	Se Alterna tive 1: Strai ght staircas e	Alterna tive 1: Left hand area	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet)	Se Alterna tive 1:Strai ght staircas e Number	Alterna tive 1: Left hand area	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x	Se Alterna tive 1:Strai ght staircas e Number	Alterna tive 1: Left hand area	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna	se Alterna tive 1: Strai ght staircas e Number of steps	Alterna tive 1: Left hand area	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft	deck floor Height from the bottom	Wall 1 distance from back	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1:	se Alterna tive 1:Strai ght staircas e Number of steps Alterna	Alterna tive 1: Left hand area width	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea	deck floor Height from the bottom	Wall 1 distance from back bulkhead	Alternative 1:	Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2	Se Alterna tive 1:Strai ght staircas e Number of steps Alterna tive	Alterna tive 1: Left hand area width	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1	Alternative 1: single bed	Cabinet move x axis	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall	Se Alterna tive 1: Strai ght staircas e Number of steps Alterna tive 1: Strai	Alterna tive 1: Left hand area width Alterna tive 1:	pit seat Seat widt
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance	Alternative 1: single bed	Cabinet move x axis Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte	Se Alterna tive 1: Strai ght staircas e Number of steps Alterna tive 1: Strai ght	Alterna tive 1: Left hand area width Alterna tive 1: Left	pit seat Seat widt h
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance from	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance from	Alternative 1: single bed	Cabinet move x axis	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte d	se Alterna tive 1: Strai ght staircas e Number of steps Alterna tive 1: Strai ght staircas	Alterna tive 1: Left hand area width Alterna tive 1: Left hand	pit seat Seat widt h
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance from the	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance	Alternative 1: single bed	Cabinet move x axis Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte d electric	se Alterna tive 1:Strai ght staircas e Number of steps Alterna tive 1:Strai ght staircas e	Alterna tive 1: Left hand area width Alterna tive 1: Left hand area	pit seat Seat widt h
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance from	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance from	Alternative 1: single bed	Cabinet move x axis Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte d	se Alterna tive 1: Strai ght staircas e Number of steps Alterna tive 1: Strai ght staircas	Alterna tive 1: Left hand area width Alterna tive 1: Left hand	pit seat Seat widt h
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance from the	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance from	Alternative 1: single bed	Cabinet move x axis Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte d electric	se Alterna tive 1:Strai ght staircas e Number of steps Alterna tive 1:Strai ght staircas e	Alterna tive 1: Left hand area width Alterna tive 1: Left hand area	pit seat Seat widt h
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance from the	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance from	Alternative 1: single bed	Cabinet move x axis Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte d electric toilet)	se Alterna tive 1: Strai ght staircas e Number of steps Alterna tive 1: Strai ght staircas e move x	Alterna tive 1: Left hand area width Alterna tive 1: Left hand area	pit seat Seat widt h
LOWER DECK	floor height Bulkhe ads Head bulkhea d distance from head of the yacht Aft bulkhea d distance from the	deck floor Height from the bottom	Wall 1 distance from back bulkhead Wall 1 Y1 distance from	Alternative 1: single bed	Cabinet move x axis Cabinet	Alterna tive 1: WCL2 (wall mounte d electric toilet) move x axis Alterna tive 1: WCL2 (wall mounte d electric toilet) move y	se Alterna tive 1: Strai ght staircas e Number of steps Alterna tive 1: Strai ght staircas e move x	Alterna tive 1: Left hand area width Alterna tive 1: Left hand area	pit seat Seat widt h



					L _	.			
	room		Distance	Move y axis	Rotation	tive 1:	tive	tive 1:	heig
	wall		from Wall 1		angle	Vetus	1: Strai	Left	ht
	distance		Y1			WCL2	ght	hand	from
	from aft					(wall	staircas	area	floor
	bulkhea					mounte	е	height	
	d					d	move y		
						electric	axis		
						toilet)			
						Rotatio			
						n angle			
						Alterna	Alterna		
			Wall 2					Alterna	
			distance			tive 2:	tive		<u> </u>
			from Wall 1	Single bed		Vetus	2: Left-	tive 2:	Seat
				Rotation		WCS2	turning	Right	back
				angle		(electri	staircas	hand	heig
						c large)	е	area	ht
						move x	move x	width	
						axis	axis		
						Alterna	Alterna		
						tive 2:	tive	Alterna	
			Wall 2 Y1			Vetus	2: Left-	tive 2:	
			distance	Alternative		WCS2	turning	Right	
			from	2:		(electri	staircas	hand	
			starboard	double bed		c large)	e	area	
						move y	move y	length	
						axis	axis	longti	
						uxi3	Alterna		
						Alterna			
						tive 2:	tive	Alterna	
			Wall 1 Y2			Vetus	3: Right	tive 2:	
			Distance	double bed		WCS2	-	Right	
			from Wall 2	Move x axis		(electri	turning	hand	
			Y1			c large)	staircas	area	
						Rotatio	е	height	
						n angle	move x	noight	
						ii angle	axis		
LOWER DECK						A.U	Alterna		
						Alterna	tive		
						tive 3:	3: Right	Alterna	
			Wall 3			Vetus	-	tive 3:	
			distance	double bed		WCS2	turning	Whole	
			from Wall 2	Move y axis		(electri	staircas	area	
						c small)	e		
						move x		length	
						axis	move y		
							axis		
						Alterna	Alterna		
						tive 3:	tive	Alterna	
			Wall 3 Y1	double bed		Vetus	4: Spiral	tive 3:	
			distance	Rotation		WCS2	staircas	Whole	
			from	angle		(electri	e	area	
			starboard	angio		c small)	move x	height	
						move y		neight	
						axis	axis		
			Wall 3 Y2	Alternative		Alterna	Alterna		
			Distance	3:		tive 3:	tive		
	1	I	I	I	I	I	1	1	l



		from Wall 3	single-	Vetus	4: Spiral	
		Y1	angled	WCS2	staircas	
				(electri	е	
				c small)	move y	
				Rotatio	axis	
				n angle		
				Alterna		
				tive 4:		
				RASKE		
		Wall 4	single-	RM69		
		distance	angled	(marin		
		from Wall 3				
		from wair 3	Move x axis	type		
				large)		
				move x		
				axis		
				Alterna		
				tive 4:		
		Wall 4 Y1		RASKE		
		distance	single-	RM69		
		from	angled	(marin		
		starboard	Move y axis	type		
		starboard		large)		
				move y		
				axis		
				Alterna		
				tive 4:		
				RASKE		
		Wall 4 Y2	Alternative	RM69		
		Distance	4:	(marin		
		from Wall 4	double-	type		
		Y1	angled	large)		
				Rotatio		
				n angle		
				Alterna		
				tive 5:		
				RASKE		
		Wall 1 X1	double-	RM69		
		rotation	angled	(marin		
		angle	Move x axis	type		
				small)		
				move x		
				axis		
				Alterna		
				tive 4:		
				RASKE		
			double-	RM69		
		Wall 1 X1	angled	(marin		
		hide/unhide	Move y axis	type		
				small)		
				move y		
				axis		
			Altornative			
LOWER DECK		Wall 1 X2	Alternative	Alterna		
		hide/unhide	5:	tive 4:		
			single berth	RASKE		



			RM69		
			(marin		
			type		
			small)		
			Rotatio		
			n angle		
	Wall 1 X3				
	rotation	single berth			
	angle	Move x axis			
	Wall 1 X3				
	hide/unhide	single berth			
		Move y axis			
	Wall 2 X1				
	rotation	Rotation			
	angle	angle			
	-	-			
		Alternative	 		
	Wall 2 X1	6:			
	hide/unhide	double			
	indo, di indo	narrow			
		beds			
		double	 		
	Wall 2 X2	narrow			
	hide/unhide	beds Move			
		x axis			
	Wall 2 X3	double			
	rotation	narrow			
	angle	beds Move			
	angle				
		y axis double			
	Wall 2 X3	narrow			
	hide/unhide	beds			
		Rotation			
	MULL O MI	angle			
	Wall 3 X1				
	rotation				
	angle				
	Wall 3 X1				
	hide/unhide				
	Wall 3 X2				
	hide/unhide				
	Wall 3 X3				
	rotation				
	angle				
	Wall 3 X3				
	hide/unhide				
]



REFERENCES

- Browning, A. W.1990. A Mathematical Model to Simulate Small Yacht Behavior, Thesis in Bournemouth Polytechnic University.
- Daniels, A. and Parsons, M.G., 2006. An Agent Based Approach to Space Allocation in General Arrangements, 9th International Marine Design Conference, Ann Arbor, Michigan, U.S.A.
- F. Pérez-Arribas, J.A. Suárez-Suárez, L. Fernández-Jambrina, Automatic surface modelling of a ship hull, In Computer-Aided Design, Volume 38, Issue 6, 2006, Pages 584-594, ISSN 0010-4485, https://doi.org/10.1016/j.cad.2006.01.013.
- Foster, I. T., 1979. Computer Aided Design, Research Project Department of Computer Science University of Cnterbury.
- Jo, J. and Gero, J., 1998. Space Layout Planning Using an Evolutionary Approach, Artificial Intelligence in Engineering, 12, pp.149–162
- Jong-Ho Nam, Dong-Ham Kim, Ho Jin Lee, An Approach to Computerized Preliminary Design Procedure of Mid-Size Superyachts from Hull Modeling to Interior Space Arrangement, in International Journal of Naval Architecture and Ocean Engineering, Volume 2, Issue 2, 2010, pages 96-103, ISSN 2092-6782, https://doi.org/10.2478/IJNAOE-2013-0024
- Harries, S. & Schulze, D. 1997. Numerical Investigation of a Systematic Model Series for the Design of Fast Monohulls, In: Proceedings of the 4th International Conference on Fast Sea Transportation (FAST'97).
- Harries, S. & Schulze, D., 1998. Parametric Design and Hydrodynamic Optimization of Ship Hull Forms Zugl.: Berlin, Techn. University, Diss.
- Larsson, L. and Eliasson, R., Principles of Yacht Design, Adlard Coles, London, U.K., 2000.
- Lee, K.Y. Han, S.N. and Roh, M.I., 2002. Optimal Compartment Layout Design for a Naval Ship Using an Improved Genetic Algorithm, Marine Technology, 39(3), pp.159-169.
- Mancuso, A., Parametric design of sailing hull shapes Parametric design of sailing hull shapes, In Ocean Engineering, Volume 33, Issue 2, 2006, Pages 234-246, ISSN 0029-8018, https://doi.org/10.1016/j.oceaneng.2005.03.007.
- URL-1: http://www.beneteau.com/us/swift-trawler/swift-trawler-50 (2016, 7 10).
- URL-2: http://www.defevereurope.eu/ (2016, 4 20).
- URL-3: http://www.selene-yachts.eu/en/selene49-trawler (2016, 11 24).